

Total light deflection in the field of an axisymmetric body at rest with full mass and spin multipole structure

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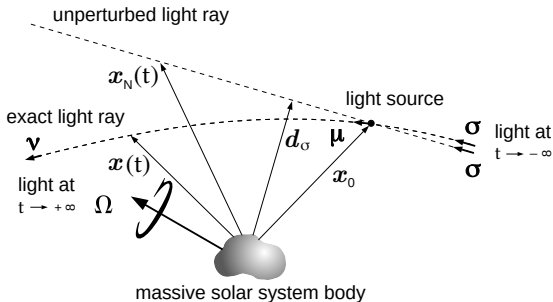
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July 14, 2023

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1.1 Light trajectory in curved space-time



- light trajectory in harmonic coordinates

$$\mathbf{x}(t) = \mathbf{x}_0 + c(t - t_0) \boldsymbol{\sigma} + \Delta \mathbf{x}(t)$$

(1)

- tangent vectors of light ray at past and future infinity

$$\boldsymbol{\sigma} = \frac{\dot{\mathbf{x}}(t)}{c} \bigg|_{t \rightarrow -\infty} \quad (2)$$

$$\boldsymbol{\nu} = \frac{\dot{\mathbf{x}}(t)}{c} \bigg|_{t \rightarrow +\infty} \quad (3)$$

- total light deflection is angle between $\boldsymbol{\sigma}$ and $\boldsymbol{\nu}$

$$\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}) = \arcsin |\boldsymbol{\sigma} \times \boldsymbol{\nu}|$$

1.2 Light deflection in field of monopole

- tangent vector at plus infinity

$$\boldsymbol{\nu} = \boldsymbol{\sigma} + \boldsymbol{\nu}_{1PN}^{M_0}$$

with

$$\boldsymbol{\nu}_{1PN}^{M_0} = -\frac{4GM}{c^2} \frac{d_{\boldsymbol{\sigma}}}{d_{\boldsymbol{\sigma}}}$$

- angle of total light deflection

$$\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1PN}^{M_0}) = \frac{4GM}{c^2} \frac{1}{d_{\boldsymbol{\sigma}}}$$

- $\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1PN}^{M_0}) = 1.75''$ for grazing ray at Sun

1.3 Light deflection in field of monopole in uniform rotation

- tangent vector at plus infinity

$$\boldsymbol{\nu} = \boldsymbol{\sigma} + \boldsymbol{\nu}_{1\text{PN}}^{M_0} + \boldsymbol{\nu}_{1.5\text{PN}}^{S_1}$$

with angular momentum $\mathbf{S} = \kappa^2 M \Omega P^2 \mathbf{e}_3$ and

$$\boldsymbol{\nu}_{1.5\text{PN}}^{S_1} = -\frac{4G}{c^3 (d_\sigma)^2} \left[2 \frac{(\boldsymbol{\sigma} \times \mathbf{d}_\sigma) \cdot \mathbf{S}}{d_\sigma} \frac{\mathbf{d}_\sigma}{d_\sigma} + (\boldsymbol{\sigma} \times \mathbf{S}) \right]$$

- angle of total light deflection: $\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1\text{PN}}^{M_0}) + \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_1})$

$$\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_1}) = \frac{4GM}{c^3 (d_\sigma)^2} \frac{(\boldsymbol{\sigma} \times \mathbf{d}_\sigma) \cdot \mathbf{S}}{d_\sigma}$$

- $\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_1}) = 0.7 \mu\text{as}$ for grazing ray at Sun

2. Tangent vector and light deflection for arbitrary body

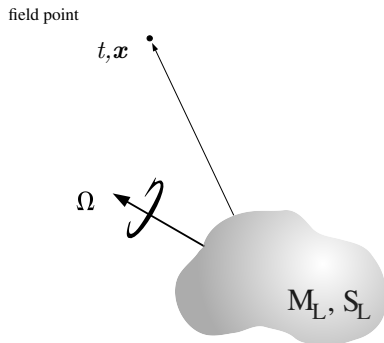
- multipole decomposition of tangent vector at future infinity

$$\boldsymbol{\nu} = \boldsymbol{\sigma} + \sum_{l=0}^{\infty} \boldsymbol{\nu}_{1\text{PN}}^{M_L} + \sum_{l=1}^{\infty} \boldsymbol{\nu}_{1.5\text{PN}}^{S_L} + \mathcal{O}(c^{-4})$$

- multipole decomposition of total light deflection

$$\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}) = \sum_{l=0}^{\infty} \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1\text{PN}}^{M_L}) + \sum_{l=1}^{\infty} \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_L}) + \mathcal{O}(c^{-4})$$

2.1 Metric of arbitrary body at rest



- post-Newtonian expansion of metric tensor

$$g_{\mu\nu}(t, \mathbf{x}) = \eta_{\mu\nu} + h_{\mu\nu}^{(2)}(t, \mathbf{x}) + h_{\mu\nu}^{(3)}(t, \mathbf{x}) + \mathcal{O}(c^{-4})$$

- metric perturbations in time-independent case [1, 2, 3]
in canonical gauge:

$$h_{00}^{(2)}(\mathbf{x}) = \frac{2}{c^2} \sum_{l=0}^{\infty} \frac{(-1)^l}{l!} \hat{M}_L \hat{\partial}_L \frac{1}{r}$$

$$h_{0i}^{(3)}(\mathbf{x}) = \frac{4}{c^3} \sum_{l=1}^{\infty} \frac{(-1)^l l}{(l+1)!} \epsilon_{iab} \hat{S}_{bL-1} \hat{\partial}_{aL-1} \frac{1}{r}$$

$$h_{ij}^{(2)}(\mathbf{x}) = \frac{2}{c^2} \delta_{ij} \sum_{l=0}^{\infty} \frac{(-1)^l}{l!} \hat{M}_L \hat{\partial}_L \frac{1}{r}$$

- with the STF differential operator

$$\hat{\partial}_L = \text{STF}_{i_1 \dots i_l} \frac{\partial}{\partial x^{i_1}} \cdots \frac{\partial}{\partial x^{i_l}}$$

2.2 The mass and spin multipoles for arbitrary body

- mass multipoles [3]

$$\hat{M}_L = \int d^3x \hat{x}_L \Sigma$$

- spin multipoles [3]

$$\hat{S}_L = \int d^3x \epsilon_{jk< i_l} \hat{x}_{L-1>} x^j \Sigma^k$$

- where $\Sigma = (T^{00} + T^{kk})/c^2$ and $\Sigma^k = T^{0k}/c$
with $T^{\alpha\beta}$ is the stress-energy tensor of body

2.3 Geodesic equation

- geodesic equation is given by

$$\begin{aligned} \frac{\ddot{x}^i(t)}{c^2} = & + \frac{\partial h_{00}^{(2)}}{\partial x^i} - 2 \frac{\partial h_{00}^{(2)}}{\partial x^j} \sigma^i \sigma^j \\ & + \frac{\partial h_{0j}^{(3)}}{\partial x^i} \sigma^j - \frac{\partial h_{0i}^{(3)}}{\partial x^j} \sigma^j - \frac{\partial h_{0j}^{(3)}}{\partial x^k} \sigma^i \sigma^j \sigma^k \end{aligned}$$

- It is **difficult to integrate the geodesic equation**, because one has **first to perform the differentiations** in metric and geodesic equation and **afterwards to insert the unperturbed light ray** and then **to perform the integrations**

2.4 Advanced integration method

- advanced integration methods by Kopeikin (1997) [4]
based on new parameters

$$c\tau = \boldsymbol{\sigma} \cdot \boldsymbol{x}_N$$

and

$$\xi^i = P_j^i x_N^j$$

- where the operator

$$P^{ij} = \delta^{ij} - \sigma^i \sigma^j$$

projects onto the plane perpendicular to vector $\boldsymbol{\sigma}$

2.5 Metric in terms of new parameters

- metric in terms of new parameters is given by

$$h_{00}^{(2)}(c\tau, \xi) = \frac{2}{c^2} \sum_{l=0}^{\infty} \frac{(-1)^l}{l!} \hat{M}_L \hat{\partial}_L \frac{1}{r_N}$$

$$h_{0i}^{(3)}(c\tau, \xi) = \frac{4}{c^3} \sum_{l=1}^{\infty} \frac{(-1)^l l}{(l+1)!} \epsilon_{iab} \hat{S}_{bL-1} \hat{\partial}_{aL-1} \frac{1}{r_N}$$

$$h_{ij}^{(2)}(c\tau, \xi) = \frac{2}{c^2} \delta_{ij} \sum_{l=0}^{\infty} \frac{(-1)^l}{l!} \hat{M}_L \hat{\partial}_L \frac{1}{r_N}$$

- with the STF differential operator

$$\begin{aligned} \hat{\partial}_L = & \text{STF}_{i_1 \dots i_l} \sum_{p=0}^l \frac{l!}{(l-p)! p!} \sigma_{i_1} \dots \sigma_{i_p} \\ & \times P_{i_{p+1}}^{j_{p+1}} \dots P_{i_l}^{j_l} \frac{\partial}{\partial \xi^{j_{p+1}}} \dots \frac{\partial}{\partial \xi^{j_l}} \left(\frac{\partial}{\partial c\tau} \right)^p \end{aligned}$$

2.6 Geodesic equation in terms of new parameters

- geodesic equation is given by

$$\frac{\ddot{x}^i(\tau)}{c^2} = P^{ij} \frac{\partial h_{00}^{(2)}}{\partial \xi^j} - \frac{\partial h_{00}^{(2)}}{\partial c\tau} \sigma^i - \frac{\partial h_{0i}^{(3)}}{\partial c\tau} + P^{ik} \frac{\partial h_{0j}^{(3)}}{\partial \xi^k} \sigma^j$$

- It is **not difficult to integrate the geodesic equation**, because one may first perform the integrations and afterwards one may perform the differentiations
- first and second integration are given by [4]

$$\frac{\dot{\mathbf{x}}(\tau)}{c} = \boldsymbol{\sigma} + \sum_{l=0}^{\infty} \frac{\Delta \dot{\mathbf{x}}_{1\text{PN}}^{M_L}(\tau)}{c} + \sum_{l=1}^{\infty} \frac{\Delta \dot{\mathbf{x}}_{1.5\text{PN}}^{S_L}(\tau)}{c}$$
$$\mathbf{x}(\tau) = \mathbf{x}_N(\tau) + \sum_{l=0}^{\infty} \Delta \mathbf{x}_{1\text{PN}}^{M_L}(\tau, \tau_0) + \sum_{l=1}^{\infty} \Delta \mathbf{x}_{1.5\text{PN}}^{S_L}(\tau, \tau_0)$$

2.7 Tangent vector of light ray for arbitrary body

- multipole decomposition of tangent vector at future infinity

$$\boldsymbol{\nu} = \boldsymbol{\sigma} + \sum_{l=0}^{\infty} \boldsymbol{\nu}_{1\text{PN}}^{M_L} + \sum_{l=1}^{\infty} \boldsymbol{\nu}_{1.5\text{PN}}^{S_L} + \mathcal{O}(c^{-4})$$

- mass-multipole term can be obtained from Eq. (34) in [4]

$$\nu_{1\text{PN}}^{i M_L} = -\frac{4G}{c^2} P^{ij} \frac{\partial}{\partial \xi^j} \frac{(-1)^l}{l!} \hat{M}_L \hat{\partial}_L \ln |\boldsymbol{\xi}|$$

- spin-multipole term can be obtained from Eq. (37) in [4]

$$\nu_{1.5\text{PN}}^{i S_L} = -\frac{8G}{c^3} P^{ij} \frac{\partial}{\partial \xi^j} \sigma^c \epsilon_{i l b c} \frac{(-1)^l}{(l+1)!} \hat{S}_{b L-1} \hat{\partial}_L \ln |\boldsymbol{\xi}|$$

2.8 Total light deflection for arbitrary body

- multipole decomposition of total light deflection

$$\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}) = \sum_{l=0}^{\infty} \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1\text{PN}}^{M_L}) + \sum_{l=1}^{\infty} \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_L}) + \mathcal{O}(c^{-4})$$

- mass-multipole term ($l \geq 2$); cf. Eq. (47) in [4]

$$\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1\text{PN}}^{M_L}) = -\frac{4G}{c^2} \frac{1}{|\boldsymbol{\xi}|} \frac{(-1)^l}{(l-1)!} \hat{M}_L \hat{\partial}_L \ln |\boldsymbol{\xi}|$$

- spin-multipole term ($l \geq 1$); cf. Eq. (48) in [4]

$$\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_L}) = -\frac{8G}{c^3} \frac{1}{|\boldsymbol{\xi}|} \epsilon_{abc} \sigma^c \frac{(-1)^l l^2}{(l+1)!} \hat{S}_{bL-1} \hat{\partial}_{aL-1} \ln |\boldsymbol{\xi}|$$

- the STF differential operation is given by

$$\hat{\partial}_L \ln |\boldsymbol{\xi}| = \text{STF}_{i_1 \dots i_l} P_{i_{p+1}}^{j_{p+1}} \dots P_{i_l}^{j_l} \frac{\partial}{\partial \xi^{j_1}} \dots \frac{\partial}{\partial \xi^{j_l}} \ln |\boldsymbol{\xi}|$$

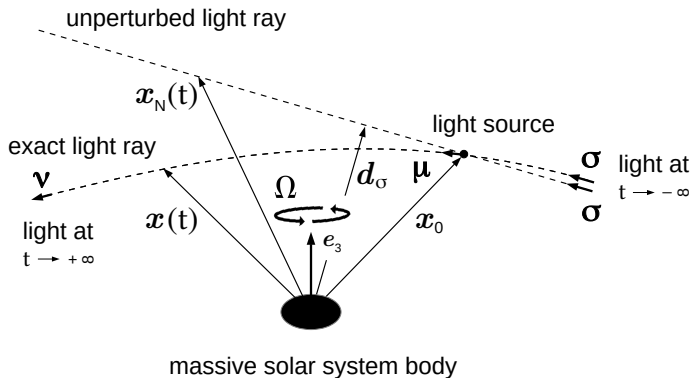
- considerable amount of algebra yields [9]:

$$\hat{\partial}_L \ln |\boldsymbol{\xi}| = \frac{(-1)^{l+1}}{|\boldsymbol{\xi}|^l} \text{STF}_{i_1 \dots i_l} \sum_{n=0}^{[l/2]} G_n^l P_{i_1 i_2} \dots P_{i_{2n-1} i_{2n}} \frac{\xi_{i_{2n+1}} \dots \xi_{i_l}}{|\boldsymbol{\xi}|^{l-2n}}$$

- where the coefficients [9]

$$G_n^l = (-1)^n 2^{l-2n-1} \frac{l!}{n!} \frac{(l-n-1)!}{(l-2n)!}$$

3. Total light deflection for axisymmetric body



- body rotates with constant Ω around its symmetry axis e_3

3.1 Mass and Spin multipoles of axisymmetric body

- mass monopole

$$\hat{M}_0 = -M (P)^0 J_0$$

- mass multipoles [5]

$$\hat{M}_L = -M (P)^l J_l \delta_{<i_1}^3 \dots \delta_{i_l}^3$$

- spin dipole (moment of inertia $\kappa^2 = I/M P^2$)

$$\hat{S}_a = -\kappa^2 M \Omega (P)^2 J_0 \delta_a^3$$

- spin multipoles [5]

$$\hat{S}_L = -M \Omega (P)^{l+1} J_{l-1} \frac{l+1}{l+4} \delta_{<i_1}^3 \dots \delta_{i_l}^3$$

- zonal harmonic coefficients [6]

$$J_l = -\frac{1}{M (P)^l} \int d^3x r^l \Sigma P_l(\cos \theta)$$

- STF tensor

$$\delta^3_{<i_1} \dots \delta^3_{i_l>} = \sum_{p=0}^{[l/2]} H_p^l \delta_{\{i_1 i_2 \dots i_{2p-1} i_{2p}} \delta^3_{i_{2p+1} \dots i_l\}}$$

- with the scalar coefficients

$$H_p^l = (-1)^p \frac{(2l - 2p - 1)!!}{(2l - 1)!!}$$

3.2 Tangent vector and light deflection: M_L

- mass-multipole term of tangent vector [9]:

$$\nu_{1\text{PN}}^i M_L = -\frac{4GM}{c^2} \frac{J_l}{l} P^{ij} \frac{\partial}{\partial \xi^j} \left(\frac{P}{|\boldsymbol{\xi}|} \right)^l F_M^l$$

- mass-multipole term of total light deflection [9]:

$$\delta \left(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1\text{PN}}^{M_L} \right) = -\frac{4GM}{c^2} \frac{J_l}{d_\sigma} \left(\frac{P}{d_\sigma} \right)^l F_M^l$$

- where the scalar function is given by

$$F_M^l = \frac{1}{(l-1)!} \delta_{<i_1}^3 \dots \delta_{i_l}^3 \sum_{n=0}^{[l/2]} G_n^l P_{i_1 i_2} \dots P_{i_{2n-1} i_{2n}} \frac{\xi_{i_{2n+1}} \dots \xi_{i_l}}{|\boldsymbol{\xi}|^{l-2n}}$$

- by algebraic calculations [9]
in agreement with time-transfer function approach [8]

$$F_M^l = \frac{1}{(l-1)!} \sum_{n=0}^{[l/2]} G_n^l \left(1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2 \right)^n \left(\frac{\mathbf{d}_\sigma \cdot \mathbf{e}_3}{d_\sigma} \right)^{l-2n}$$

- by introducing the variable $-1 \leq x \leq +1$

$$x = \left(1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2 \right)^{-1/2} \left(\frac{\mathbf{d}_\sigma \cdot \mathbf{e}_3}{d_\sigma} \right)$$

one may write the scalar function in the form [9]:

$$F_M^l = \left[1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2 \right]^{[l/2]} \frac{l}{2} \sum_{n=0}^{[l/2]} \frac{(-1)^n (l-n-1)!}{n! (l-2n)!} (2x)^{l-2n}$$

3.2.1 Chebyshev polynomials of first kind

$$T_l(x) = \frac{l}{2} \sum_{n=0}^{[l/2]} \frac{(-1)^n}{n!} \frac{(l-n-1)!}{(l-2n)!} (2x)^{l-2n}$$

- scalar function (mass multipoles) (for $l \geq 0$) [9]:

$$F_M^l = \left[1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2 \right]^{[l/2]} T_l(x)$$

- tangent vector $\boldsymbol{\nu}_{1.\text{PN}}^{M_L}$ and total light deflection $\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.\text{PN}}^{M_L})$ caused by mass-multipoles M_L are given in terms of Chebyshev polynomials of first kind $T_l(x)$

3.2.2 Example: mass quadrupole

- Chebyshev polynomial of first kind and second degree:

$$T_2(x) = -1 + 2x^2$$

- mass-quadrupole term of total light deflection [7]:

$$\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{\text{1PN}}^{M_2}) = + \frac{4GM}{c^2} \frac{J_2}{d_\sigma} \left(\frac{P}{d_\sigma} \right)^2 \\ \times \left[1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2 - 2 \left(\frac{\mathbf{d}_\sigma \cdot \mathbf{e}_3}{d_\sigma} \right)^2 \right]$$

3.2.3 Example: mass octupole

- Chebyshev polynomial of first kind and fourth degree:

$$T_4(x) = 1 - 8x^2 + 8x^4$$

- mass-octupole term of total light deflection:

$$\begin{aligned} \delta(\boldsymbol{\sigma}, \nu_{\text{IPN}}^{M_4}) = & -\frac{4GM}{c^2} \frac{J_4}{d_\sigma} \left(\frac{P}{d_\sigma}\right)^4 \\ & \times \left[\left(1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2\right)^2 - 8 \left(\frac{\mathbf{d}_\sigma \cdot \mathbf{e}_3}{d_\sigma}\right)^2 \left(1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2\right) \right. \\ & \left. + 8 \left(\frac{\mathbf{d}_\sigma \cdot \mathbf{e}_3}{d_\sigma}\right)^4 \right] \end{aligned}$$

3.2.4 Upper limits of total light deflection: mass multipoles

- The upper limit of Chebyshev polynomial of first kind:

$$T_l(x) = \cos(l \arccos x) \implies |T_l(x)| \leq 1$$

- Upper limits of total light deflection for mass multipoles [9]:

$$\left| \delta \left(\boldsymbol{\sigma}, \boldsymbol{\nu}_{\text{1PN}}^{M_L} \right) \right| \leq \frac{4GM}{c^2} \frac{|J_l|}{d_\sigma} \left(1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2 \right)^{[l/2]} \left(\frac{P}{d_\sigma} \right)^l$$

$$\left| \delta \left(\boldsymbol{\sigma}, \boldsymbol{\nu}_{\text{1PN}}^{M_L} \right) \right| \leq \frac{4GM}{c^2} \frac{|J_l|}{d_\sigma} \left(\frac{P}{d_\sigma} \right)^l$$

$$\left| \delta \left(\boldsymbol{\sigma}, \boldsymbol{\nu}_{\text{1PN}}^{M_L} \right) \right| \leq \frac{4GM}{c^2} \frac{|J_l|}{d_\sigma}$$

3.3 Tangent vector and light deflection: S_L

- spin-multipole term of tangent vector [9]:

$$\nu_{1.5\text{PN}}^{i S_L} = -\frac{8GM}{c^3} \Omega P \frac{J_{l-1}}{l+4} P^{ij} \frac{\partial}{\partial \xi^j} \left(\frac{P}{|\xi|} \right)^l F_S^l$$

- spin-multipole term of total light deflection [9]:

$$\delta \left(\sigma, \nu_{1.5\text{PN}}^{S_L} \right) = -\frac{8GM}{c^3} \Omega J_{l-1} \left(\frac{P}{d_\sigma} \right)^{l+1} F_S^l$$

- where the scalar function is given by

$$F_S^l = \frac{1}{(l-1)!} \frac{l}{l+4} \epsilon_{ilbc} \sigma^c \delta_{<b}^3 \delta_{i_1}^3 \dots \delta_{i_{l-1}}^3 \\ \times \text{STF}_{i_1 \dots i_l} \sum_{n=0}^{[l/2]} G_n^l P_{i_1 i_2} \dots P_{i_{2n-1} i_{2n}} \frac{\xi_{i_{2n+1}} \dots \xi_{i_l}}{|\xi|^{l-2n}}$$

- by algebraic calculations [9]:

$$F_S^l = + \frac{(\boldsymbol{\sigma} \times \mathbf{d}_\sigma) \cdot \mathbf{e}_3}{d_\sigma} \frac{l}{l+4} \frac{1}{(l-1)!} \\ \times \sum_{n=0}^{[l/2]} G_n^l \frac{l-2n}{l} \left(1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2 \right)^n \left(\frac{\mathbf{d}_\sigma \cdot \mathbf{e}_3}{d_\sigma} \right)^{l-2n-1}$$

- by introducing the variable x as defined above one obtains

$$F_S^l = \frac{(\boldsymbol{\sigma} \times \mathbf{d}_\sigma) \cdot \mathbf{e}_3}{d_\sigma} \frac{l}{l+4} \left[1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2 \right]^{[l/2]} \\ \times \sum_{n=0}^{[l/2]} (l-2n) \frac{(-1)^n}{n!} \frac{(l-n-1)!}{(l-2n)!} (2x)^{l-2n-1}$$

- using

$$(l - 2n) (2x)^{l-2n-1} = \frac{1}{2} \frac{d}{dx} (2x)^{l-2n}$$

- one may write the scalar function in the form [9]:

$$F_S^l = \frac{(\boldsymbol{\sigma} \times \mathbf{d}_\sigma) \cdot \mathbf{e}_3}{d_\sigma} \frac{1}{l+4} \left[1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2 \right]^{[l/2]} \frac{dT_l(x)}{dx}$$

- derivative of Chebyshev polynomial of first kind related to Chebyshev polynomial of second kind

$$\frac{dT_l(x)}{dx} = l U_{l-1}(x)$$

3.3.1 Chebyshev polynomials of second kind

$$U_l(x) = \sum_{n=0}^{[l/2]} \frac{(-1)^n}{n!} \frac{(l-n)!}{(l-2n)!} (2x)^{l-2n}$$

- spin-dipole term of total light deflection:

$$\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_1}) = -\frac{4GM}{c^3} \Omega \kappa^2 J_0 \left(\frac{P}{d_\sigma}\right)^2 \frac{(\boldsymbol{\sigma} \times \mathbf{d}_\sigma) \cdot \mathbf{e}_3}{d_\sigma}$$

- scalar function (spin multipoles) (for $l \geq 3$) [9]:

$$F_S^l = \frac{(\boldsymbol{\sigma} \times \mathbf{d}_\sigma) \cdot \mathbf{e}_3}{d_\sigma} \left[1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2\right]^{[l/2]} U_{l-1}(x)$$

- tangent vector $\boldsymbol{\nu}_{1.5\text{PN}}^{S_L}$ and total light deflection $\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_L})$ caused by spin-multipoles S_L are given in terms of Chebyshev polynomials of second kind $U_l(x)$

3.3.2 Example: spin hexapole

- Chebyshev polynomial of second kind and second degree:

$$U_2(x) = -1 + 4x^2$$

- spin-hexapole term of total light deflection:

$$\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_3}) = +\frac{24}{7} \frac{GM}{c^3} \Omega J_2 \left(\frac{P}{d_\sigma}\right)^4 \frac{(\boldsymbol{\sigma} \times \mathbf{d}_\sigma) \cdot \mathbf{e}_3}{d_\sigma} \\ \times \left[1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2 - 4 \left(\frac{\mathbf{d}_\sigma \cdot \mathbf{e}_3}{d_\sigma}\right)^2 \right]$$

3.3.3 Example: spin decapole

- Chebyshev polynomial of second kind and fourth degree:

$$U_4(x) = 1 - 12x^2 + 16x^4$$

- spin-decapole term of total light deflection:

$$\begin{aligned} \delta(\boldsymbol{\sigma}, \nu_{1.5\text{PN}}^{S_5}) = & -\frac{40}{9} \frac{GM}{c^3} \Omega J_4 \left(\frac{P}{d_\sigma}\right)^6 \frac{(\boldsymbol{\sigma} \times \mathbf{d}_\sigma) \cdot \mathbf{e}_3}{d_\sigma} \\ & \times \left[\left(1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2\right)^2 - 12 \left(\frac{\mathbf{d}_\sigma \cdot \mathbf{e}_3}{d_\sigma}\right)^2 \left(1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2\right) \right. \\ & \left. + 16 \left(\frac{\mathbf{d}_\sigma \cdot \mathbf{e}_3}{d_\sigma}\right)^4 \right] \end{aligned}$$

3.3.4 Upper limits of total light deflection: spin multipoles

- The upper limit of Chebyshev polynomial of second kind:

$$U_{l-1}(x) = \frac{1}{\sqrt{1-x^2}} \sin(l \arccos x) \implies |U_{l-1}(x)| \leq l$$

- Upper limits of total light deflection for spin multipoles [9]:

$$|\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_L})| \leq \frac{8GM}{c^3} \frac{\Omega l^2}{l+4} |J_{l-1}| \left(\frac{P}{d_\sigma}\right)^{l+1} \left(1 - (\boldsymbol{\sigma} \cdot \mathbf{e}_3)^2\right)^{\frac{l-1}{2}}$$

$$|\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_L})| \leq \frac{8GM}{c^3} \Omega \frac{l^2}{l+4} |J_{l-1}| \left(\frac{P}{d_\sigma}\right)^{l+1}$$

$$|\delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_L})| \leq \frac{8GM}{c^3} \Omega \frac{l^2}{l+4} |J_{l-1}|$$

4. Numerical values of total light deflection

Light deflection	Sun	Jupiter	Saturn
$ \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1\text{PN}}^{M_0}) $	1.75×10^6	16.3×10^3	5.8×10^3
$ \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1\text{PN}}^{M_2}) $	0.35	239	94
$ \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1\text{PN}}^{M_4}) $	1.72	9.6	5.41
$ \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1\text{PN}}^{M_6}) $	0.07	0.55	0.50
$ \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1\text{PN}}^{M_8}) $	0.007	0.04	0.06
$ \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1\text{PN}}^{M_{10}}) $	—	0.003	0.01

Light deflection	Sun	Jupiter	Saturn
$ \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_1}) $	0.7	0.17	0.04
$ \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_3}) $	—	0.026	0.008
$ \delta(\boldsymbol{\sigma}, \boldsymbol{\nu}_{1.5\text{PN}}^{S_5}) $	—	0.001	—

5. Summary

- mass-multipole terms of tangent vector and total light deflection are given in terms of Chebyshev polynomials of first kind.
- spin-multipole terms of tangent vector and total light deflection are given in terms of Chebyshev polynomials of second kind.
- strict upper limits for mass-multipole terms of total light deflection.
- strict upper limits for spin-multipole terms of total light deflection.

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